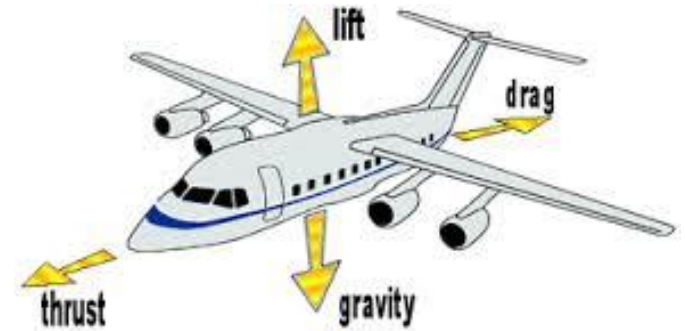
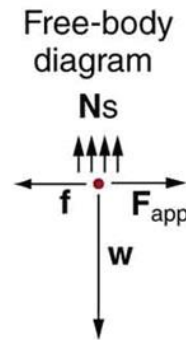
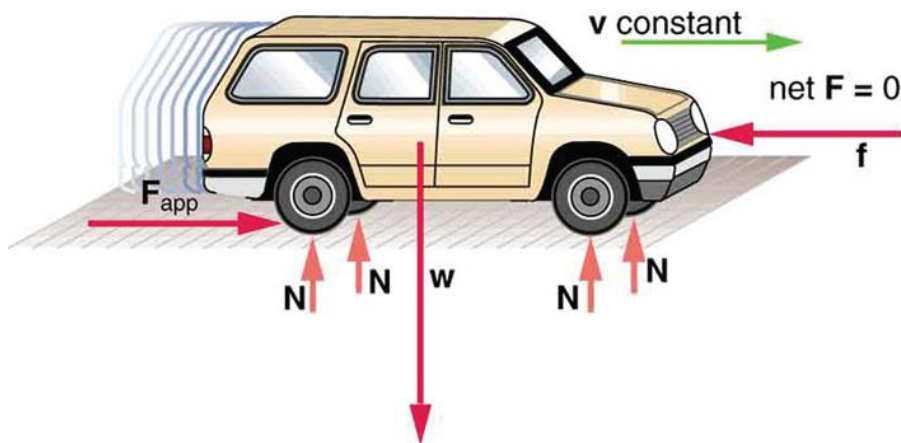
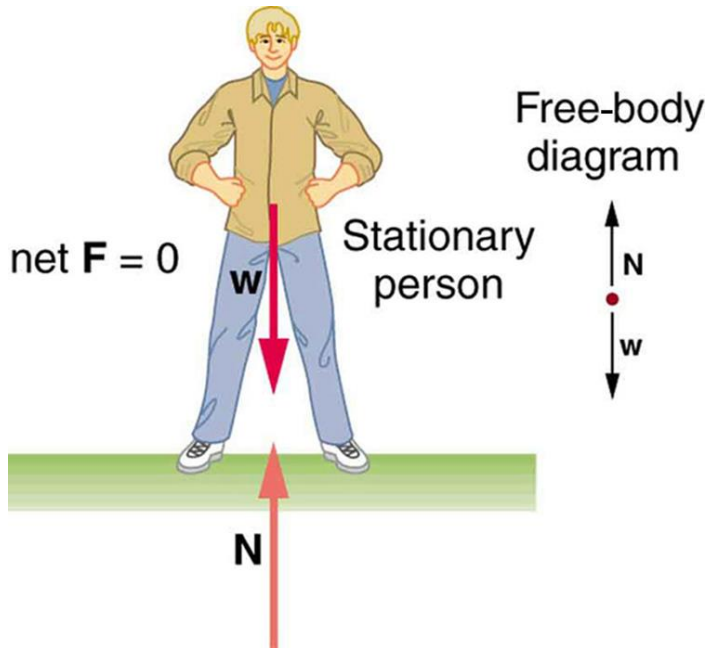
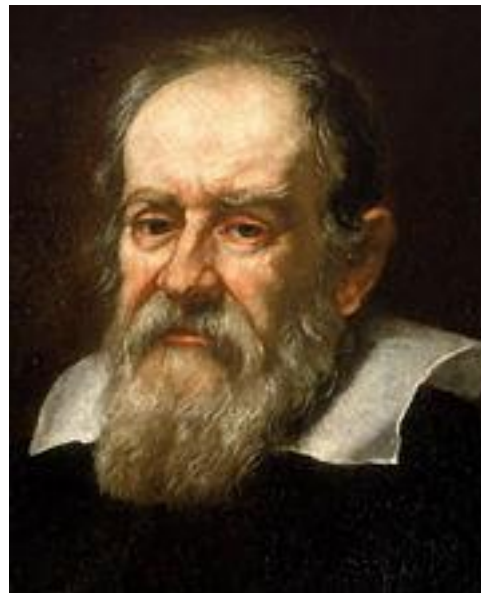
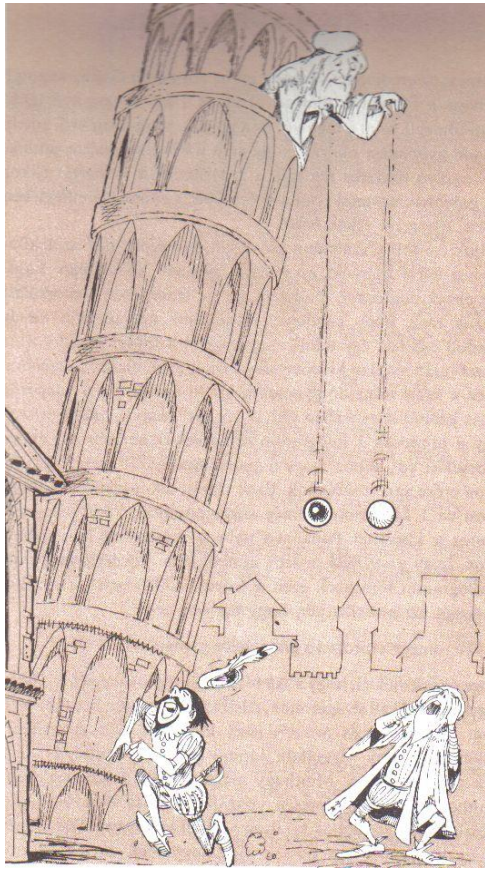


# Laws of motion



# Laws of motion & forces

Aristoteles → Galilei → Newton



Galileo Galilei  
(1564 – 1642)

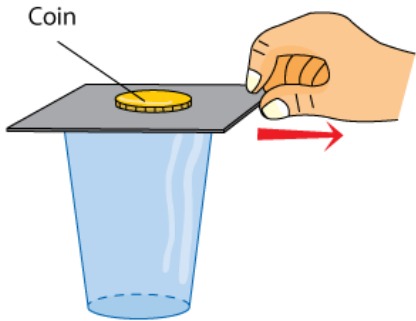


Sir Isaac Newton  
(1642. – 1727.)

Def.: Linear momentum:  $\vec{p} = m\vec{v}$   $\left[ \text{kg} \frac{\text{m}}{\text{s}} = \text{Ns} \right]$

**Newton's laws:** (point mass, inertial frame of reference)

1. The law of inertia

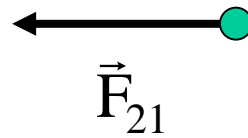
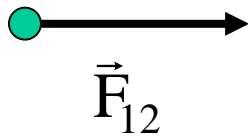


If  $\vec{F}_{\text{net}} = 0 \Rightarrow \vec{a} = 0$  ("No force, no acc.")

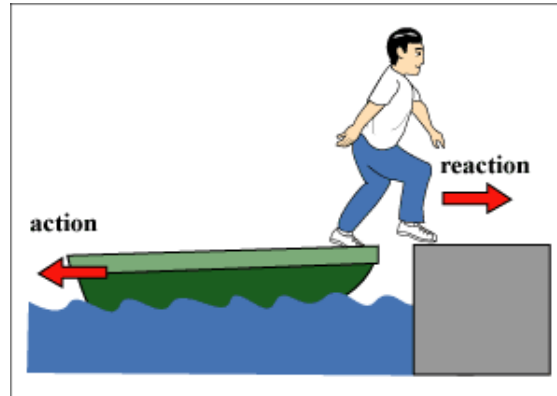
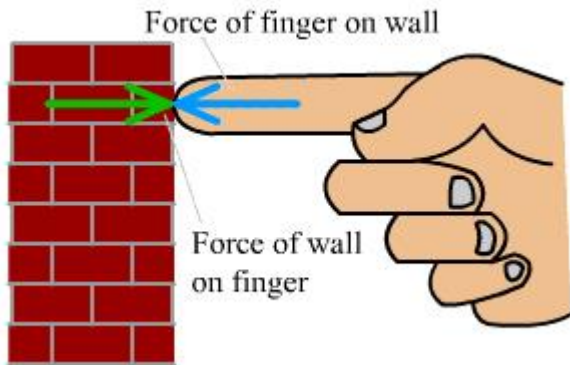
2.  $\vec{F} = m \cdot \vec{a} \rightarrow \vec{F} = m \cdot \vec{a} = m \frac{\Delta \vec{v}}{\Delta t} = \frac{\Delta \vec{p}}{\Delta t}$   $\left[ \text{kg} \frac{\text{m}}{\text{s}^2} = \text{N} \right]$

Def.: Impulse:  $\vec{I} = \vec{F} \Delta t = \vec{p}(t_2) - \vec{p}(t_1) = \Delta \vec{p}$   
 $\uparrow$   
 $\vec{F}_{\text{ave}}$

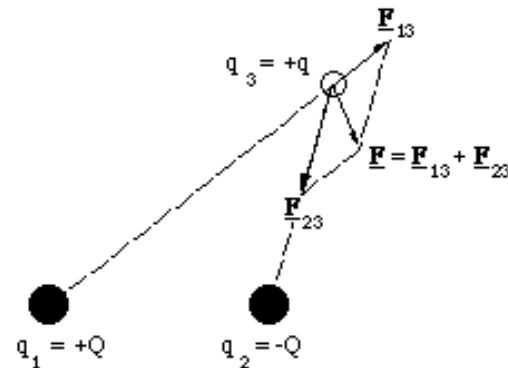
### 3. The law of action - reaction



$$\vec{F}_{12} = -\vec{F}_{21}$$



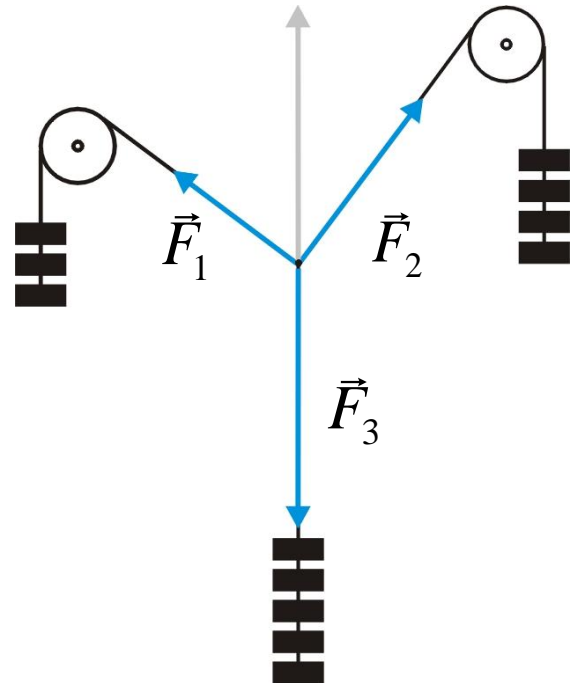
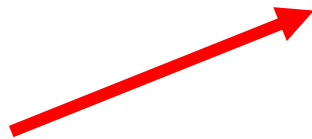
### 4. Superposition theorem: $\vec{F}_{\text{net}} = \sum_i \vec{F}_i$



$$\Sigma \vec{F} = m \Sigma \vec{a}$$

$$\sum_i \vec{F}_i = 0$$

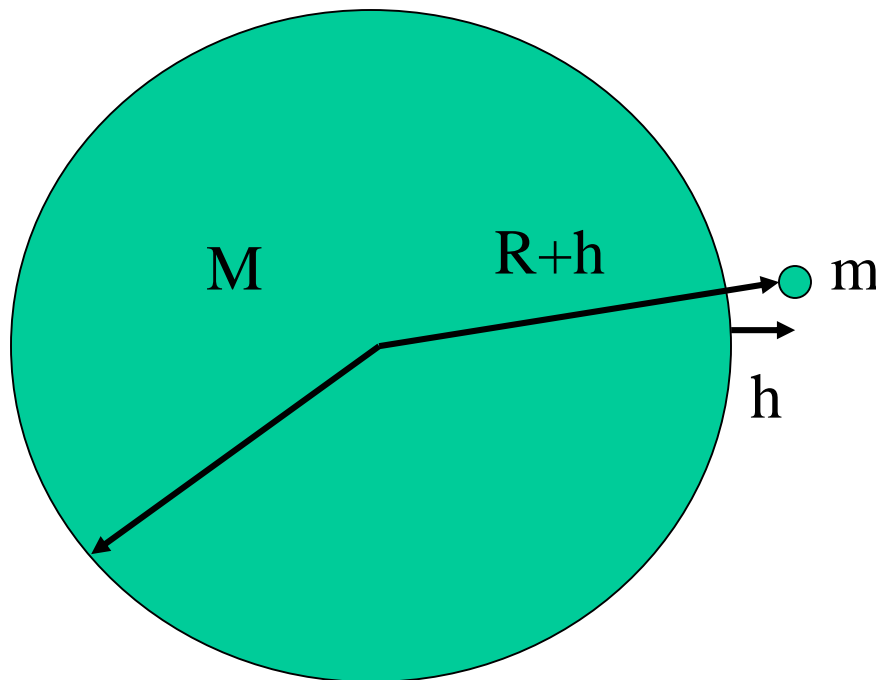
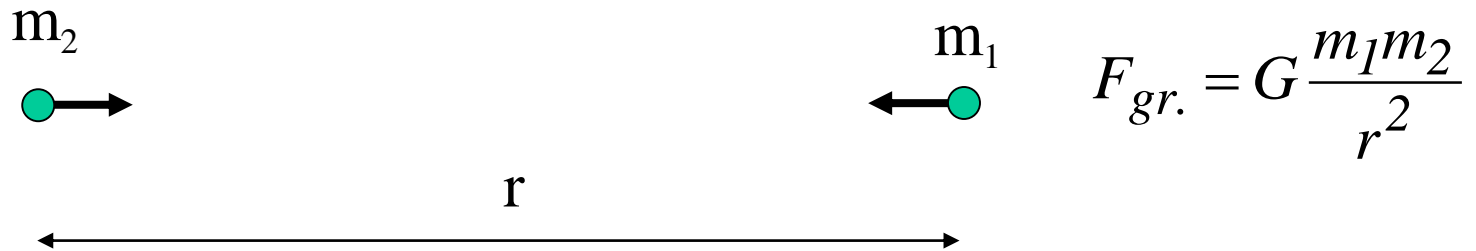
Equilibrium



# Force

$$G = 6,67 \cdot 10^{-11} \text{ Nm}^2/\text{kg}^2$$

## 1. Weight, the force of gravity



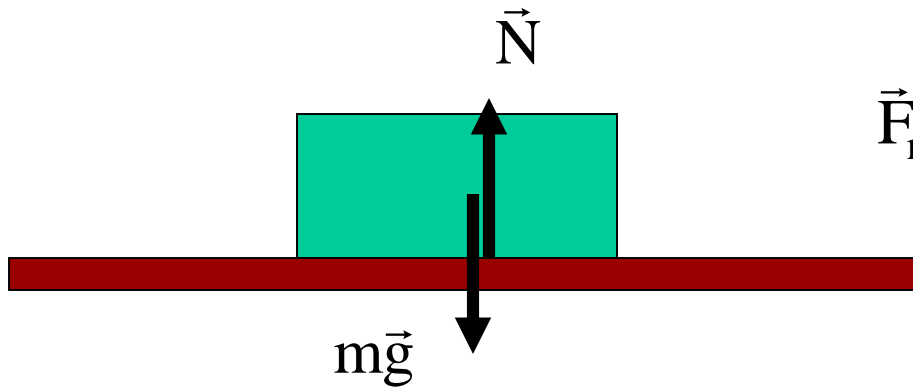
$$h \ll R$$

$$F_{gr.} = G \frac{mM}{(R+h)^2} \approx G \frac{mM}{R^2}$$

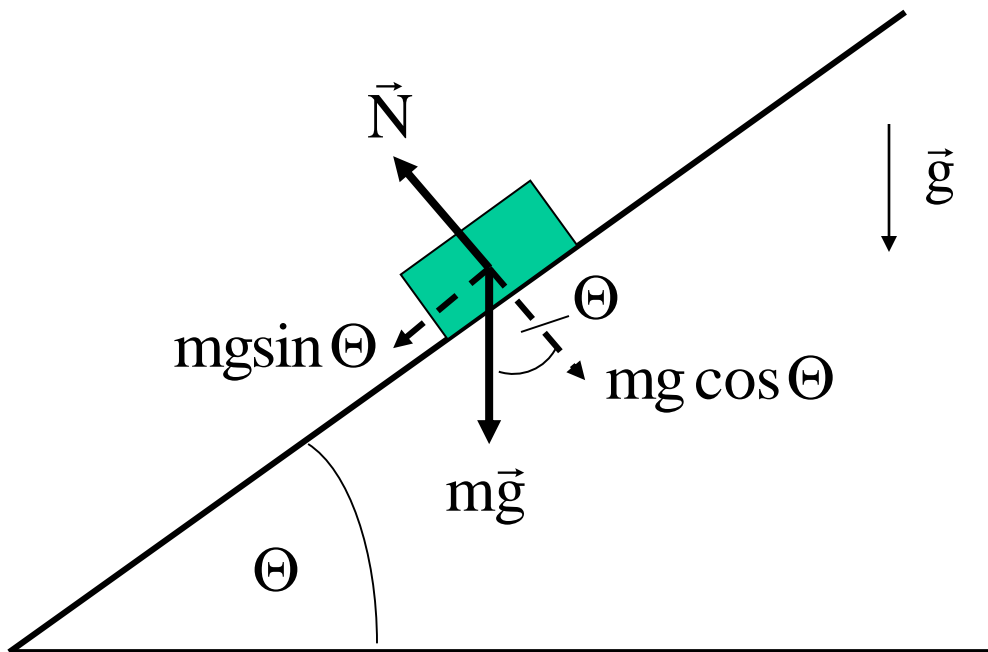


$$F_{gr.} = G \frac{Mm}{R^2} = mg \Rightarrow g = G \frac{M}{R^2}$$

## 2. Normal force

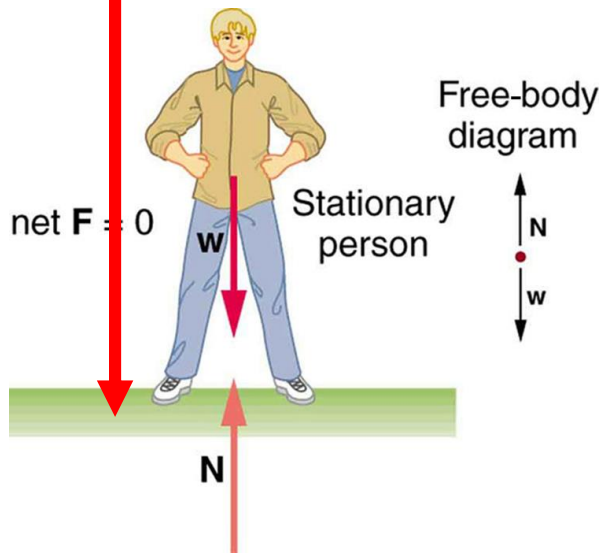


$$\vec{F}_{\text{net}} = m\vec{g} + \vec{N} = 0 \Rightarrow N = mg$$



$$N = mg \cos \Theta$$

$$|\vec{N} + m\vec{g}| = mg \cdot \sin \Theta$$

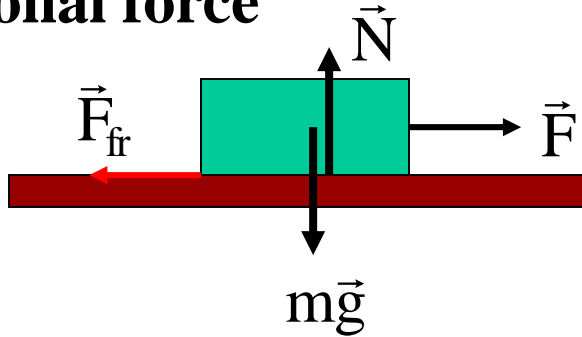


$$m = \frac{|\vec{N}|}{g}$$

$$\text{weight} = |\vec{F}_{gr.}| = |\vec{N}|$$



### 3. Frictional force



Static friction

(Object is at rest,  $F_{net}=0 \Rightarrow a=0$ )

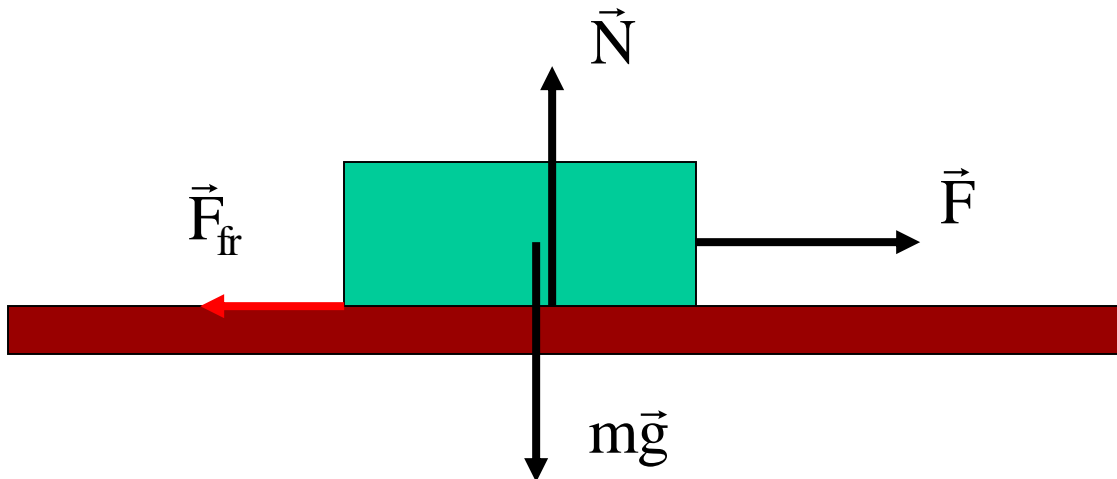
$$F_{fr} \leq \mu_o N$$

Coefficient of static friction:  $\mu_o$

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Coefficient of static friction:  $\mu_o$

The object is sliding



$$F_{fr} = \mu_k N$$

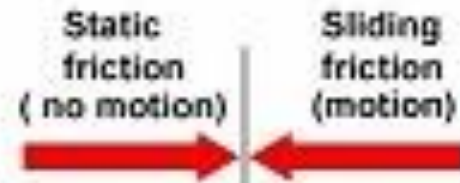
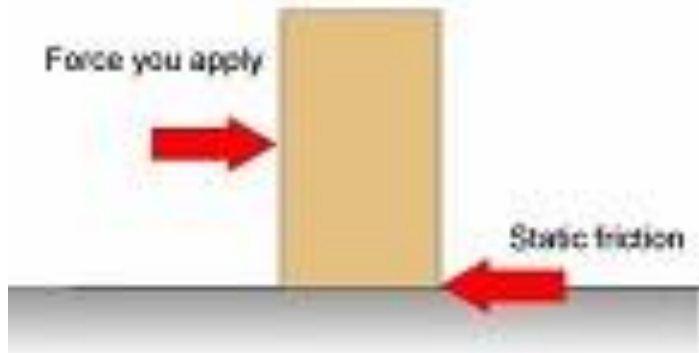
$$\mu_k \leq \mu_o$$

# Friction Forces

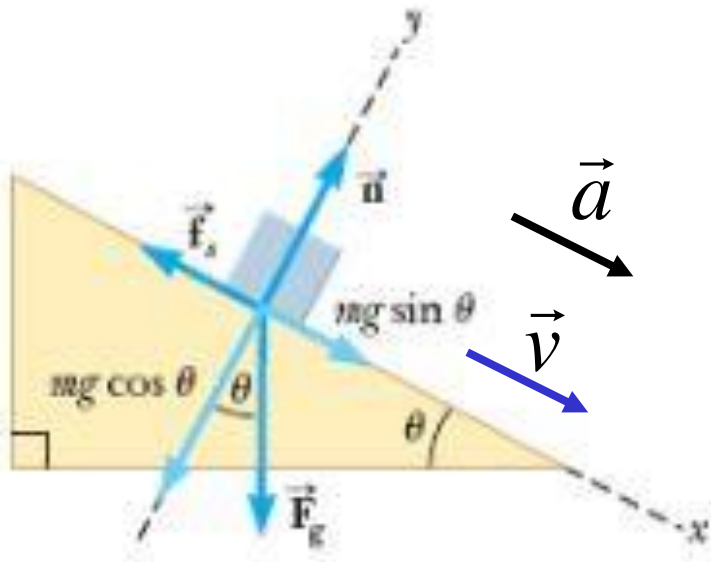
Pushing a box



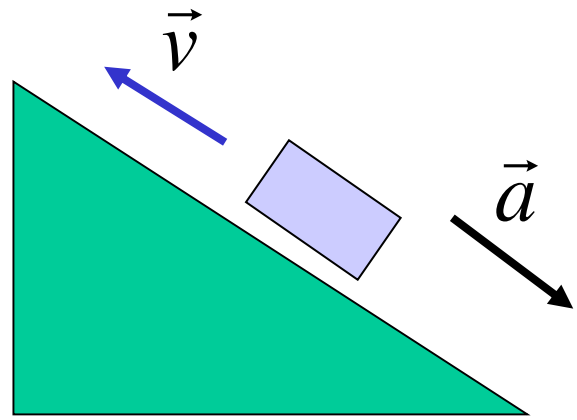
Free body diagram



$$\mu_k \leq \mu_o$$

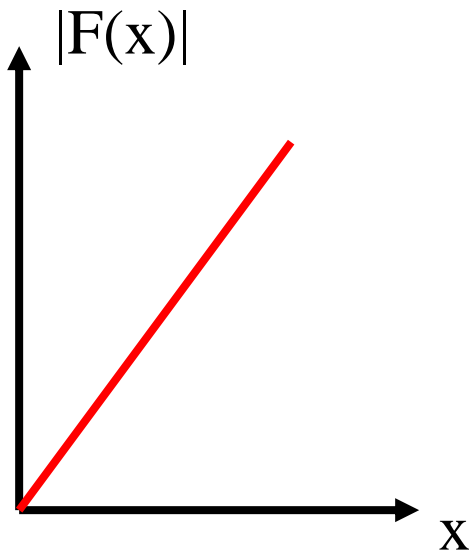
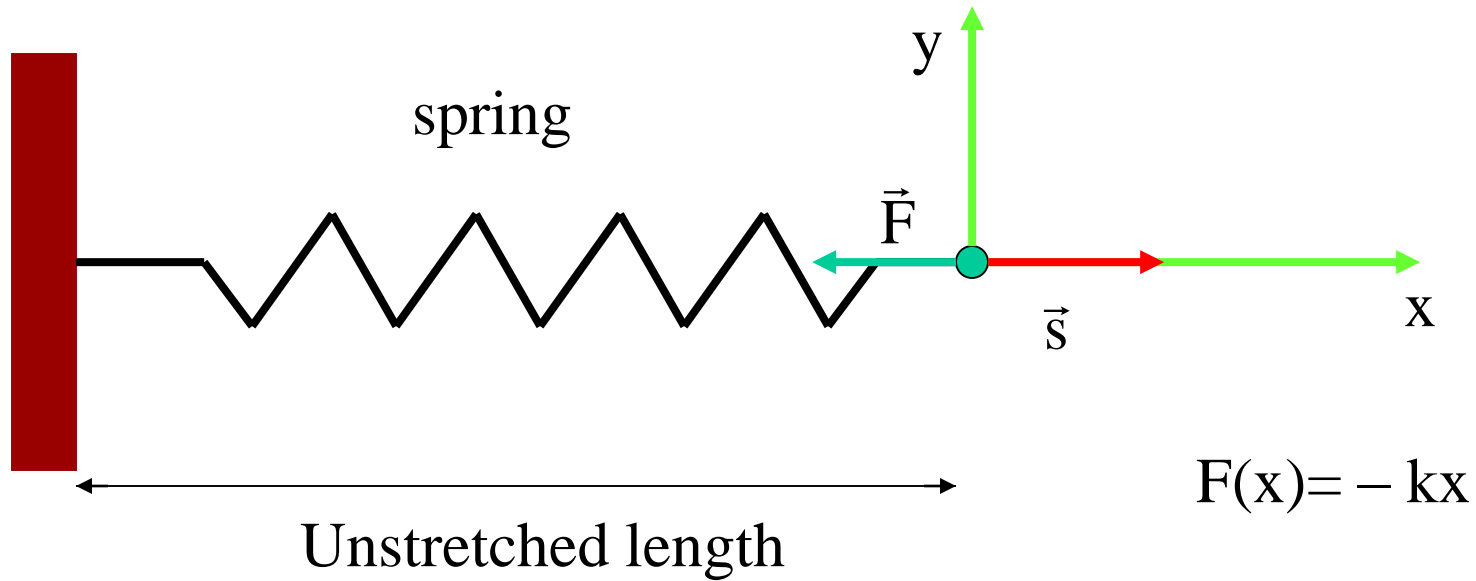


$$\vec{a} = ?$$



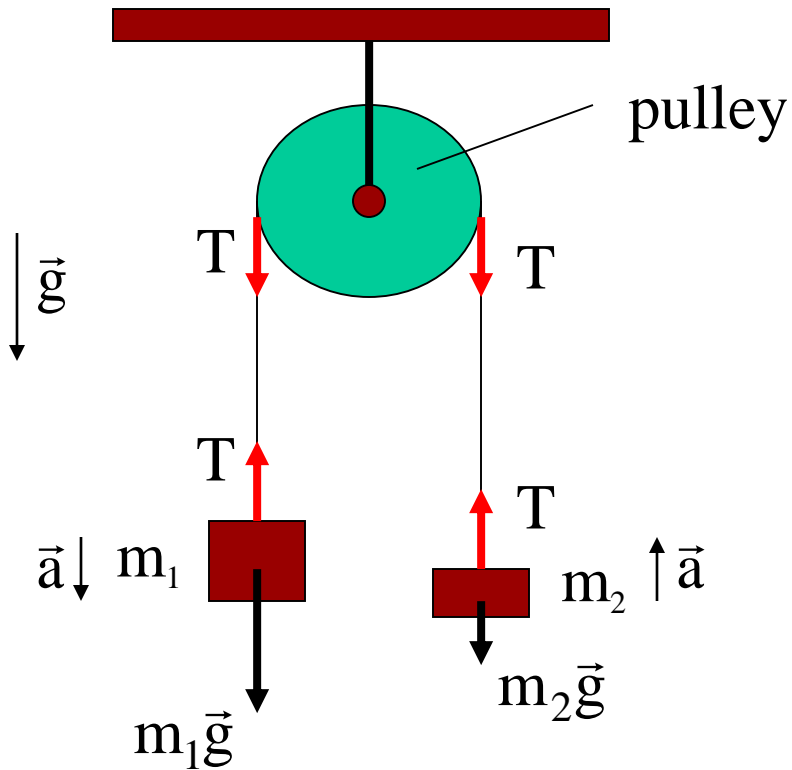
$$\vec{a}' = ?$$

## 4. Spring force



Spring constant:  $k$   $\left[ \frac{\text{N}}{\text{m}} \right]$

## 5. Tension (in the string)



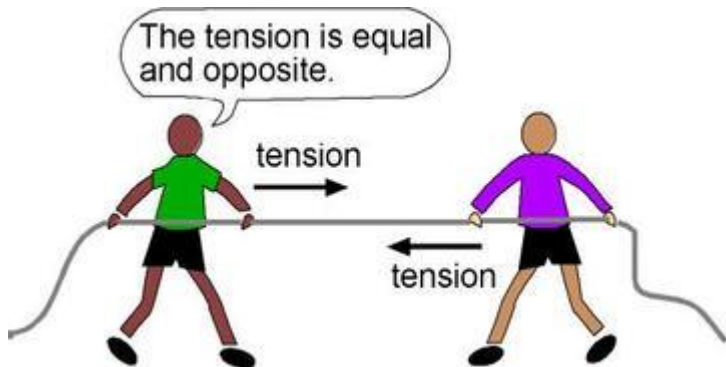
$m_1g$  ,  $m_2g$  : weight

$T$  : tension

$T = ?$        $a = ?$

I.       $m_1g - T = m_1a$

II.       $T - m_2g = m_2a$



$$a = \frac{m_1g - m_2g}{m_1 + m_2}$$

$$T = \frac{2m_1m_2}{m_1 + m_2}g$$