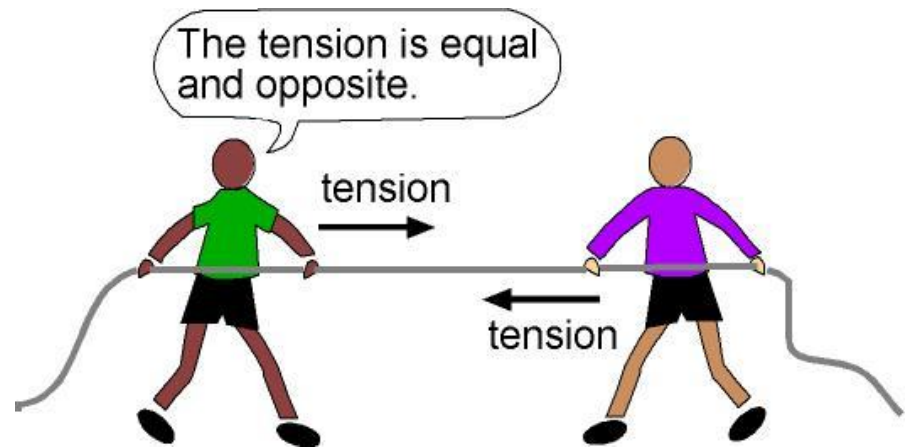
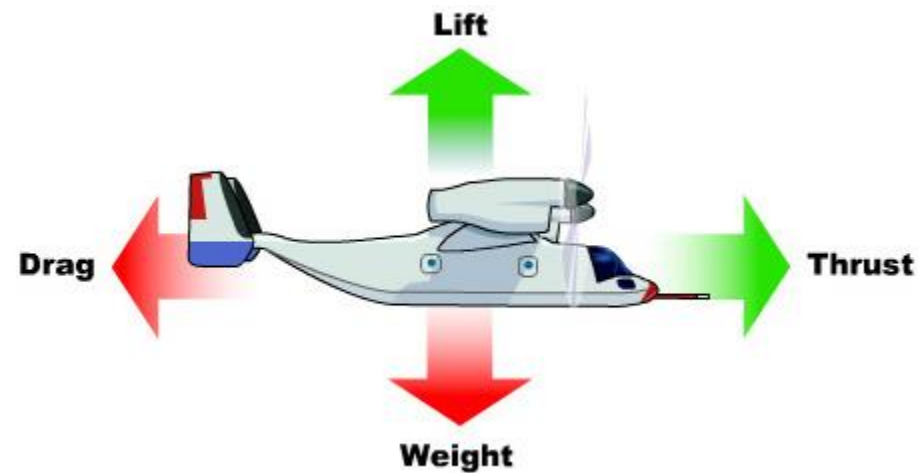




# Vectors



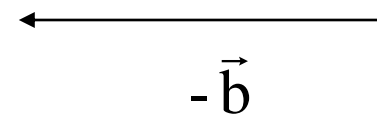
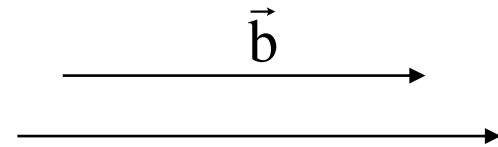
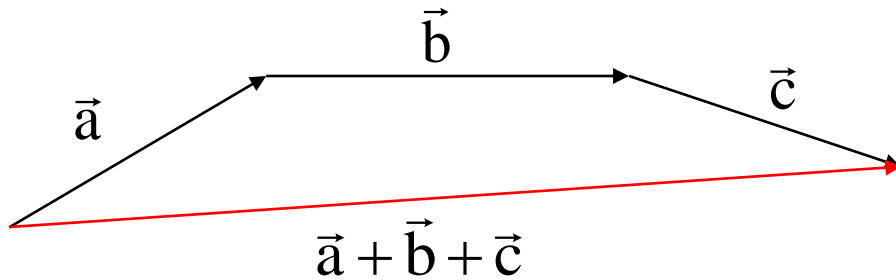
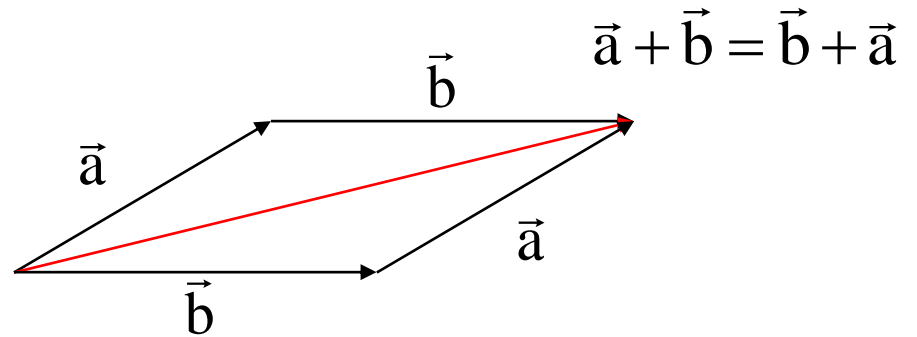
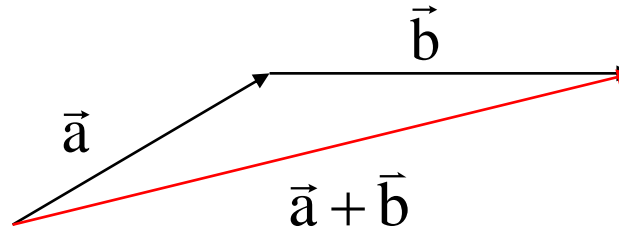
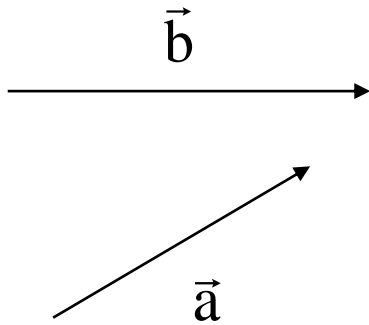
$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

*Electric force*                      *Magnetic force*

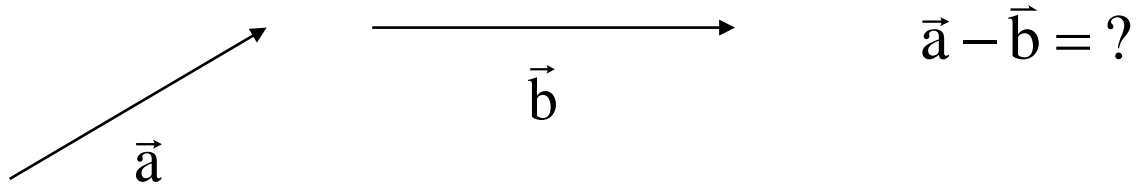
# Vectors

## Vector geometry

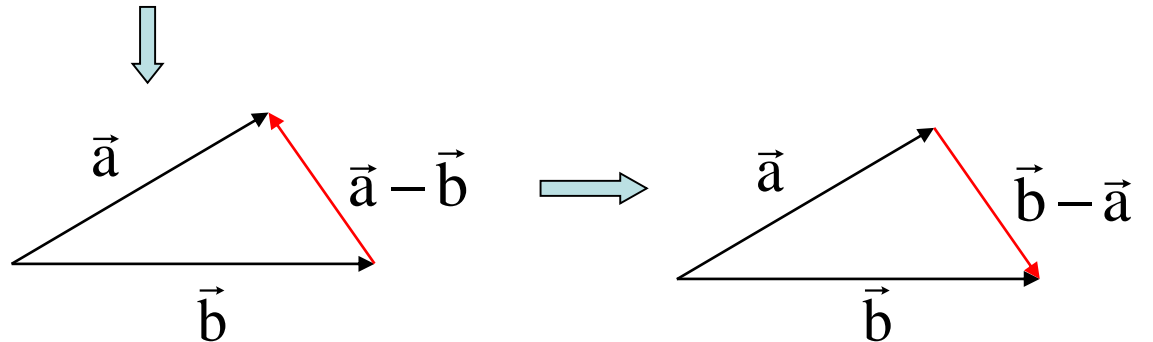
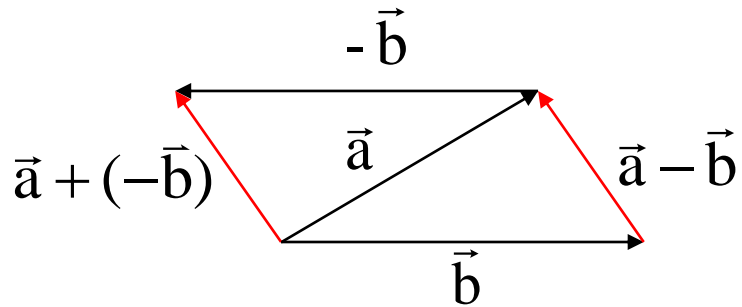
### Addition of vectors:



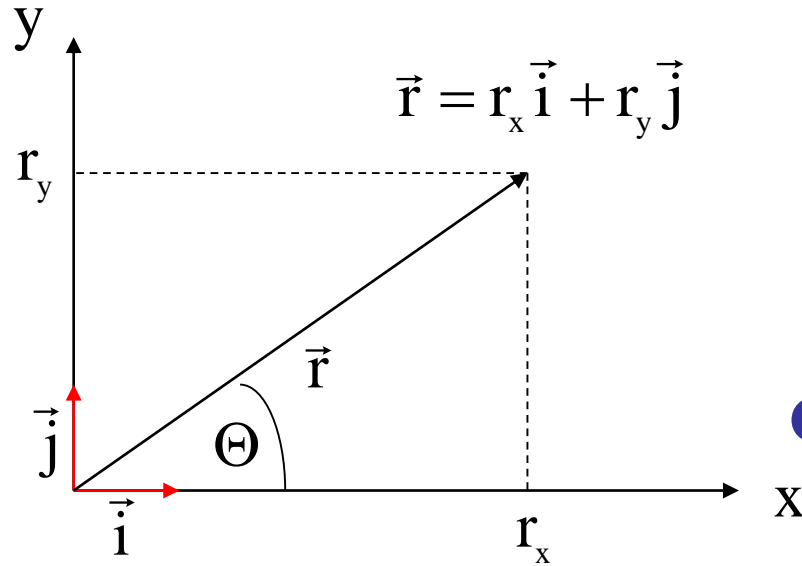
# Subtraction of vectors



$$\vec{a} - \vec{b} = \vec{a} + (-\vec{b})$$



# Coordinates & unit vectors



$$|\vec{r}| = r = \sqrt{r_x^2 + r_y^2}$$

$$\tan\Theta = \frac{r_y}{r_x}$$

**Cartesian coordinates:**  $r_x$  &  $r_y$

$$|\vec{i}| = |\vec{j}| = 1$$

**Polar coordinates :**  $r$  &  $\Theta$

$$r_x = r \cdot \cos \Theta$$

$$r_y = r \cdot \sin \Theta$$

$$\vec{r} = (r, \Theta)$$

$$\vec{r} = (r_x, r_y)$$

# Vector algebra

$$\vec{a} = a_x \vec{i} + a_y \vec{j} \quad \vec{b} = b_x \vec{i} + b_y \vec{j} \quad \vec{a} + \vec{b} = ?$$

$$\vec{a} + \vec{b} = \underline{(a_x + b_x)} \vec{i} + \underline{(a_y + b_y)} \vec{j} = \vec{d}$$

$\uparrow$   
 $d_x$

$\uparrow$   
 $d_y$

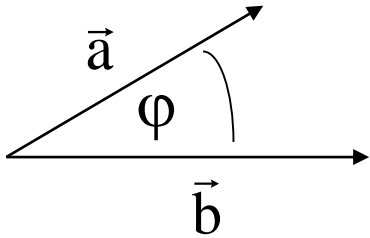
$$\vec{a} - \vec{b} = \underline{(a_x - b_x)} \vec{i} + \underline{(a_y - b_y)} \vec{j} = \vec{c}$$

$\uparrow$   
 $c_x$

$\uparrow$   
 $c_y$

$$\vec{a} + \vec{b} + \vec{c} + \dots = (a_x + b_x + c_x + \dots) \vec{i} + (a_y + b_y + c_y + \dots) \vec{j}$$

# Scalar product



**Def.:**  $\vec{a} \cdot \vec{b} = |\vec{a}| \cdot |\vec{b}| \cos \varphi$



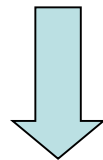
$$\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = 1 \quad \& \quad \vec{i} \cdot \vec{j} = 0$$

$$\vec{a} = a_x \vec{i} + a_y \vec{j}$$

$$\vec{b} = b_x \vec{i} + b_y \vec{j}$$

$$\vec{a} \cdot \vec{b} = ?$$

$$\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z$$



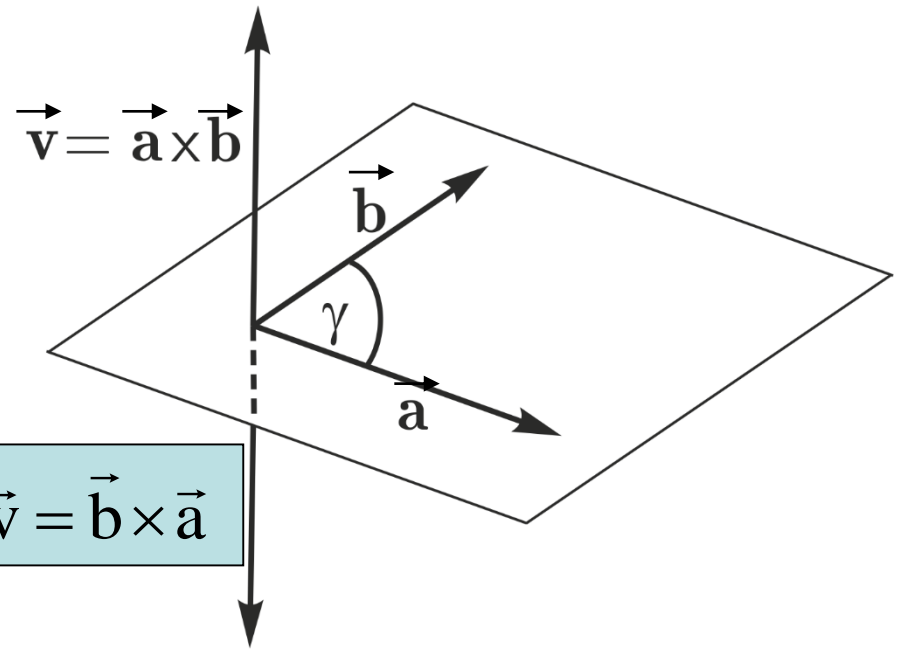
$$\cos \varphi = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| \cdot |\vec{b}|}$$

**Superposition**

**Example: work**

$$W = \vec{F} \cdot \vec{s}$$

# Vector product (cross product)



$$|\vec{a} \times \vec{b}| = |\vec{a}| \cdot |\vec{b}| \sin \gamma$$

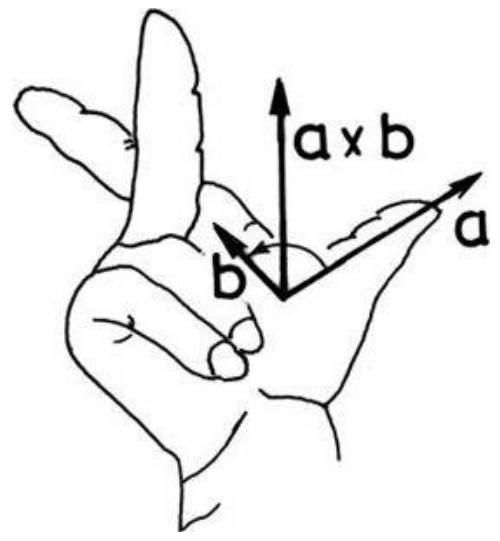


$$\vec{i} \times \vec{j} = \vec{k} \quad \& \quad \vec{j} \times \vec{k} = \vec{i}$$

$$-\vec{v} = \vec{b} \times \vec{a}$$

$$\& \quad \vec{k} \times \vec{i} = \vec{j}, \text{ but: } \vec{i} \times \vec{i} = \vec{j} \times \vec{j} = \vec{k} \times \vec{k} = 0$$

Right hands rule:



**Example: torque**

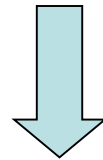
$$\vec{\tau} = \vec{r} \times \vec{F}$$

# Components of vector product

Determinant

$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = ?$$

$$\vec{a} \times \vec{b} = (a_y b_z - a_z b_y) \cdot \vec{i} + (a_z b_x - a_x b_z) \cdot \vec{j} + (a_x b_y - a_y b_x) \cdot \vec{k}$$



**Superposition**



## II. Trigonometry

$$\sin(\alpha \underline{+} \beta) = \sin \alpha \cos \beta \underline{+} \cos \alpha \sin \beta$$

$$\sin(2\alpha) = 2 \sin \alpha \cos \alpha$$

$$\cos(\alpha \underline{+} \beta) = \cos \alpha \cos \beta \underline{-} \sin \alpha \sin \beta$$

$$\cos(2\alpha) = \cos^2 \alpha - \sin^2 \alpha$$

$$\text{H.W.: } \operatorname{tg}(2\alpha) = ?$$

$$\operatorname{tg}(\alpha \underline{+} \beta) = \frac{\operatorname{tg} \alpha \underline{+} \operatorname{tg} \beta}{1 \underline{-} \operatorname{tg} \alpha \operatorname{tg} \beta}$$

$$\cos(3\alpha) = ?$$

$$\sin^2 \alpha + \cos^2 \alpha = 1$$

$$\cos\left(\frac{\alpha}{2}\right) = ?$$